

# Weighted Particle Method

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# Content

1D-1D Vlasov-Poisson equation

Usual numerical schemes

Weighted Particle method

Numerical results

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# 1D-1D Vlasov-Poisson equation

$$\left| \begin{array}{l} \partial_t f(t, x, v) + v \partial_x f(t, x, v) + E(t, x) \partial_v f(t, x, v) = 0, \end{array} \right. \quad (1.1a)$$

$$\left| \begin{array}{l} E = \partial_x \Phi, \quad \partial_x^2 \Phi(t, x) = \rho(t, x), \end{array} \right. \quad (1.1b)$$

$$\left| \begin{array}{l} f(0, x, v) = f_0(x, v), \end{array} \right. \quad (1.1c)$$

where  $t \geq 0$ ,  $v \in \mathbb{R}$ ,  $x \in \mathbb{T}$  and *charge density*:

$$\rho(t, x) := \int_{\mathbb{R}} \left( f(t, x, v) - \frac{1}{|\mathbb{T}|} \int_{\mathbb{T}} f(t, y, v) dy \right) dv.$$

## Some properties of VP

- Transport equation  $\rightarrow f$  constant along characteristics
- $(x, v) \mapsto (X(s; t, x, v), V(s; t, x, v))$  measure-preserving
- Conservation of  $\mathbb{L}^p$  norms
- Conservation of energy  $\mathcal{E}$  and momentum  $\mathcal{M}$

$$\mathcal{E}(t) := \int |v|^2 f(t, x, v) dx dv + \int |\partial_x \Phi(t, x)|^2 dx = \text{const.},$$

$$\mathcal{M}(t) = \int v f(t, x, v) dx dv = \text{const.}$$

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## Usual numerical schemes

Splitting:

$$\begin{aligned}\partial_t f(t, x, v) + v \partial_x f(t, x, v) &= 0 \\ \implies f(t, x, v) &= f(0, x - tv, v)\end{aligned}$$

$$\begin{aligned}\partial_t f(t, x, v) + E(t, x) \partial_v f(t, x, v) &= 0 \\ \implies f(t, x, v) &\approx f(0, x, v - tE(0, x))\end{aligned}$$

Grid-based methods:

- Eulerian
- (Forward/Backward) Semi-Lagrangian

Particle methods:

- (Particle/Cloud)-In-Cell

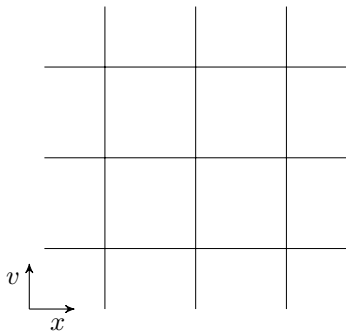
## Grid-based methods

Most common: Backwards  
Semi-Lagrangian.

Lie splitting:

$$f(t^{n+1}, x_i, v_j) \approx f(t^n, \tilde{x}_i, \tilde{v}_j).$$

- sequence of 1D steps, even in  $n$ -D
- relies on a grid (costly for high-dimensional problems)
- interpolation introduces another source of approximations
- precision cannot be finer than grid





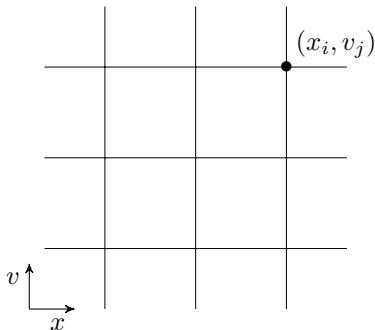
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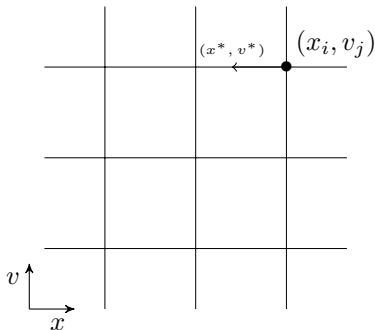
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Lie splitting:

$$x^* := x_i + (t^{n+1} - t^n)v_j, \quad v^* := v_j$$



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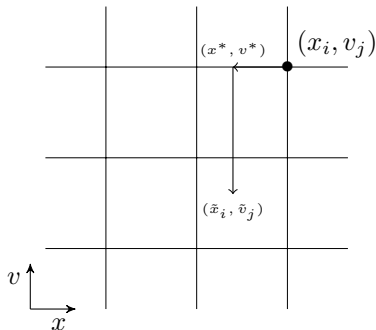
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$$v^* := v_j$$

$$\tilde{x}_i := x^*,$$

$$\tilde{v}_j = v^* + (t^{n+1} - t^n)\partial_x \Phi[f^*]$$



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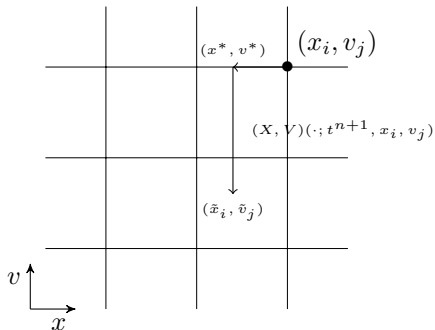
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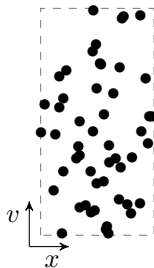


# Particle methods

Most common: Particle-In-Cell

$$f(t, x, v) \approx \sum_{p=1}^P w_p \delta_{X_p(t)}(x) \delta_{V_p(t)}(v).$$

- cheap in high-dimensional settings (Monte-Carlo integrations)
- “noisy” numerical results  $\rightarrow$  high number of particles

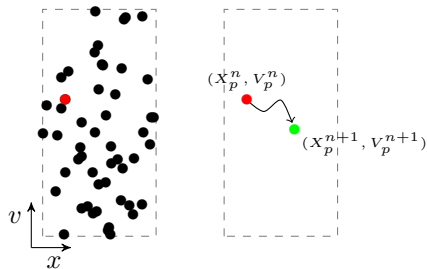


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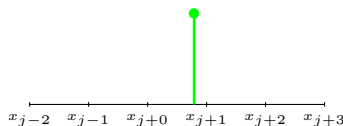
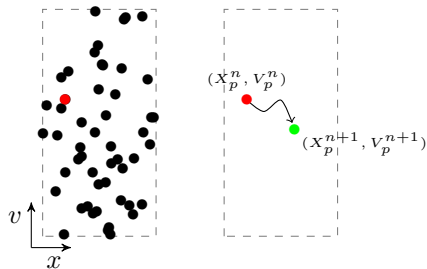


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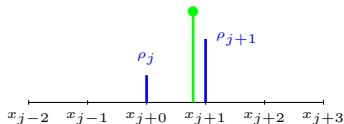
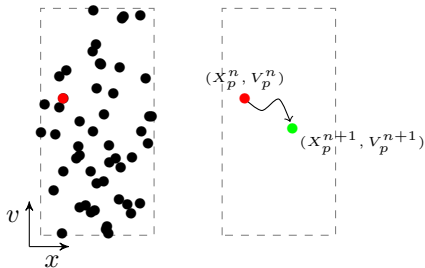


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**Weighted Particle method**

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# Weighted Particle Method

Initially introduced and used by Barré et al<sup>1</sup>, proof of convergence in<sup>2</sup>.  
Main idea: solve the Poisson equation explicitly in Fourier.

$$E(t, x) = \frac{1}{|\mathbb{T}|} \sum_{k \in \mathbb{Z}^*} \frac{1}{2\pi \left| \frac{k}{L} \right|^2} \frac{k}{L} \left[ \sin \left( 2\pi k \cdot \frac{x}{L} \right) C_k(t) - \cos \left( 2\pi k \cdot \frac{x}{L} \right) S_k(t) \right],$$

where

$$C_k(t) := \int_{\mathbb{T} \times \mathbb{R}} \cos \left( 2\pi k \frac{y}{L} \right) f(t, y, v) dy dv,$$

$$S_k(t) := \int_{\mathbb{T} \times \mathbb{R}} \sin \left( 2\pi k \frac{y}{L} \right) f(t, y, v) dy dv.$$

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<sup>1</sup>Julien Barré, Alain Olivetti, and Yoshiyuki Y Yamaguchi. “Algebraic Damping in the One-Dimensional Vlasov Equation”. In: *Journal of Physics A: Mathematical and Theoretical* 44.40 (Oct. 2011), p. 405502. ISSN: 1751-8113, 1751-8121. DOI: [10.1088/1751-8113/44/40/405502](https://doi.org/10.1088/1751-8113/44/40/405502).

<sup>2</sup>YLH. “Grid-free Weighted Particle method applied to the Vlasov-Poisson equation”. en. In: 2022, p. 40. URL: <https://hal.science/hal-03736227>.

Measure-preserving property:

$$\begin{aligned} C_k(t) &= \int_{\mathbb{T} \times \mathbb{R}} \cos\left(2\pi k \frac{y}{L}\right) f(t, y, v) dy dv \\ &= \int_{\mathbb{T} \times \mathbb{R}} \cos\left(2\pi k \frac{X(t; 0, x, u)}{L}\right) f_0(x, u) dx du, \end{aligned}$$

and

$$\begin{aligned} S_k(t) &= \int_{\mathbb{T} \times \mathbb{R}} \sin\left(2\pi k \frac{y}{L}\right) f(t, y, v) dy dv \\ &= \int_{\mathbb{T} \times \mathbb{R}} \sin\left(2\pi k \frac{X(t; 0, x, u)}{L}\right) f_0(x, u) dx du. \end{aligned}$$

→ quadrature in  $(x, u)$  → time-integration for each  $(x_i, u_j)$ .

Weighted Dirac particles appear naturally!

Truncation to  $|k| \leq K$ ,  $K \in \mathbb{N}^*$ 

$$E^K(t, x) = \frac{1}{|\mathbb{T}|} \sum_{\substack{k \in \mathbb{Z}^* \\ |k| \leq K}} \frac{1}{2\pi} \frac{1}{\left|\frac{k}{L}\right|^2} \frac{k}{L} \left[ \sin\left(2\pi k \cdot \frac{x}{L}\right) C_k^K(t) - \cos\left(2\pi k \cdot \frac{x}{L}\right) S_k^K(t) \right].$$

# Truncation to $|k| \leq K, K \in \mathbb{N}^*$

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$$\begin{cases} \frac{dX^K(t; s, x, v)}{dt} = V^K(t; s, x, v), & X^K(s; s, x, v) = x \\ \frac{dV^K(t; s, x, v)}{dt} = E^K(t, X^K(t; s, x, v)), & V^K(s; s, x, v) = v \end{cases}$$

## Truncation to $|k| \leq K$ , $K \in \mathbb{N}^*$

$$E^K(t, x) = \frac{1}{|\mathbb{T}|} \sum_{\substack{k \in \mathbb{Z}^* \\ |k| \leq K}} \frac{1}{2\pi \left| \frac{k}{L} \right|^2} \frac{k}{L} \left[ \sin \left( 2\pi k \cdot \frac{x}{L} \right) C_k^K(t) - \cos \left( 2\pi k \cdot \frac{x}{L} \right) S_k^K(t) \right].$$

$$\begin{cases} \frac{dX^K(t; s, x, v)}{dt} = V^K(t; s, x, v), & X^K(s; s, x, v) = x \\ \frac{dV^K(t; s, x, v)}{dt} = E^K(t, X^K(t; s, x, v)), & V^K(s; s, x, v) = v \end{cases}$$

$$C_k^K(t) = \int_{\mathbb{T}^d \times \mathbb{R}^d} \cos \left( 2\pi k \cdot \frac{X^K(t; 0, y, v)}{L} \right) f_0(y, v) dy dv,$$

$$S_k^K(t) = \int_{\mathbb{T}^d \times \mathbb{R}^d} \sin \left( 2\pi k \cdot \frac{X^K(t; 0, y, v)}{L} \right) f_0(y, v) dy dv.$$

## A few remarks

- Need characteristics forward in time (easy).
- Choice of quadratures & time-integration (high-order, can even be symplectic thanks to Hamiltonian structure!).
- In practice, need to truncate  $k \in \mathbb{Z}^*$  to  $|k| \leq K$ .
- Non-Uniform Fast Fourier Transform (NUFFT) can be used to accelerate computation of  $C^K, S^K$ .
- Particle method with no deposition step, so easily provable rates of convergence.

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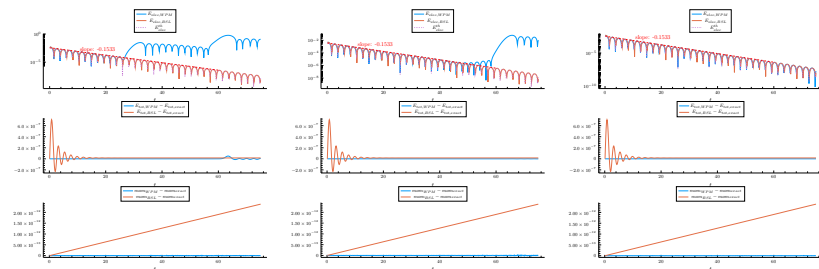


# Weak Landau damping

$$f_0(x, v) = (1 + \alpha \cos(k_x x)) \exp(-v^2/2) \frac{1}{\sqrt{2\pi}}, \quad x \in [0, L], v \in [-v_{\max}, v_{\max}].$$

The numerical parameters are

$$v_{\max} = 12, k_x = 0.5, \alpha = 0.001, \Delta t = 0.1.$$



(a)  $K = 1, N_1 = 64,$   
 $N_2 = 64$

(b)  $K = 1, N_1 = 128,$   
 $N_2 = 128$

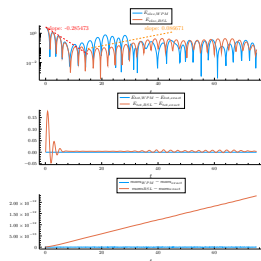
(c)  $K = 1, N_1 = 256,$   
 $N_2 = 256$

# Strong Landau damping

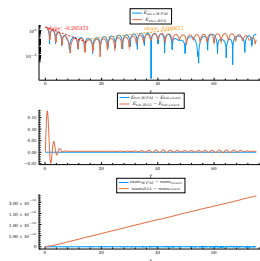
$$f_0(x, v) = (1 + \alpha \cos(k_x x)) \exp(-v^2/2) \frac{1}{\sqrt{2\pi}}, \quad x \in [0, L], v \in [-v_{\max}, v_{\max}].$$

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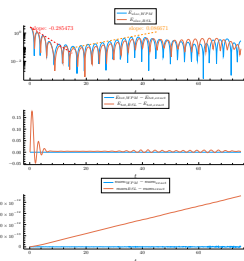
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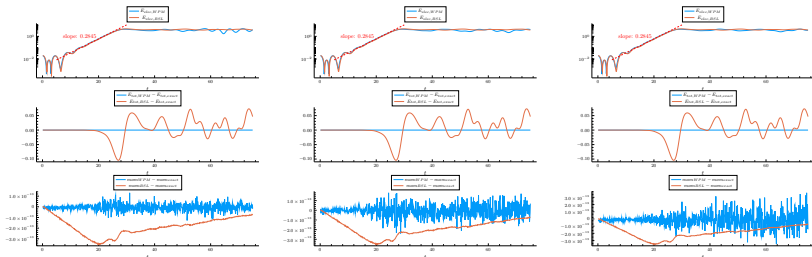
(c)  $K = 1, N_1 = 256,$   
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## Two-stream Instability

$$f_0(x, v) = (1 + \alpha \cos(k_x x)) \frac{1}{2\sqrt{2\pi}} \left( \exp\left(-\frac{(v - v_0)^2}{2}\right) + \exp\left(-\frac{(v + v_0)^2}{2}\right) \right),$$

for  $x \in [0, 2\pi/k_x]$ ,  $v \in [-v_{\max}, v_{\max}]$ . The numerical parameters are

$$\alpha = 0.001, v_{\max} = 12, k_x = 0.2, v_0 = 3, \Delta t = 0.1.$$



(a)  $K = 1$ ,  $N_1 = 64$ ,  
 $N_2 = 64$

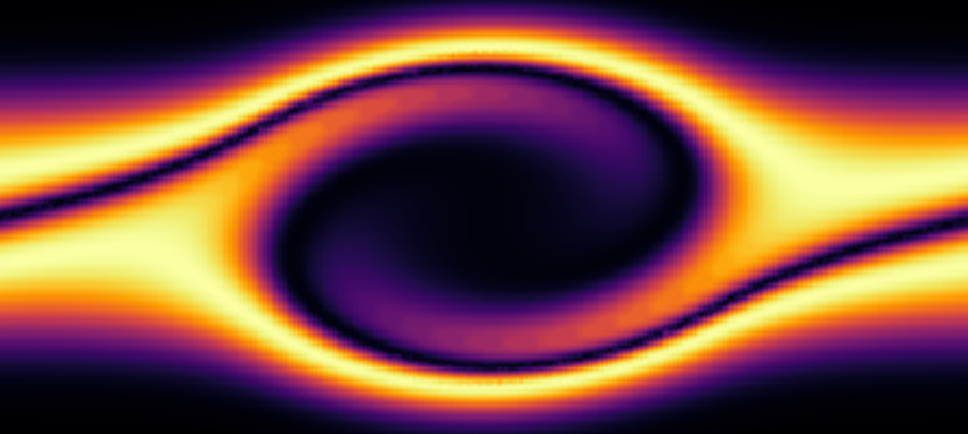
(b)  $K = 1$ ,  $N_1 = 128$ ,  
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(c)  $K = 1$ ,  $N_1 = 256$ ,  
 $N_2 = 256$

# Perspectives

- Use Monte-Carlo integration
- Consider collisions in (1.1a)
- Compare with PIC and BSL in high-dimension

Thank you!



Two-Stream instability, triangulated WPM,  $T = 30$ ,  $K = 10$ ,  $256 \times 256$  pts

# Content

Weighted Sobolev spaces

Error estimate

Numerical results with  $K = 15$

# Weighted Sobolev spaces

$$\|f\|_{\mathcal{H}_\nu^r}^2 = \sum_{\substack{(m,p,q) \in (\mathbb{N}^d)^3 \\ |p|+|q| \leq r \\ |m| \leq \nu}} \int_{\mathbb{T} \times \mathbb{R}} |v^m \partial_x^p \partial_v^q f(x, v)|^2 dv dx.$$

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## Theorem (Convergence of the Weighted Particle method)

Let  $j \in \mathbb{N}$  such that  $j \geq 1 + \max_i q_i$ , and  $\nu, r, \alpha \in \mathbb{N}$  such that  $\nu + j > d/2$ ,  $r \geq \max(3(\nu + j), (j - 1)(d + 1))$ ,  $\alpha \geq 2(r + d)$ . Let  $K \in \mathbb{N}$ , and assume  $f_0 \in \mathcal{H}_{\nu+j}^{r+\alpha}$ .

Then there exists a constant  $C > 0$  such that the following holds: for  $\delta \geq 0$ , define finite intervals  $I_{d+1} := [a_1, b_1], \dots, I_{2d} = [a_d, b_d]$  and  $I_\nu := I_{d+1} \times \dots \times I_{2d}$  such that

$$\|f_0\|_{\mathcal{H}_\nu^0(\mathbb{T}_L^d \times (\mathbb{R}^d \setminus I_\nu))} \leq \delta.$$

Then for all  $K \in \mathbb{N}^*$ , and  $n = 1, \dots, N_t$

$$\begin{aligned} & \max_{p=1, \dots, P} (|X_p^{K,n} - X(t^n; 0, x_p, v_p)| + |V_p^{K,n} - V(t^n; 0, x_p, v_p)|) \\ & \leq C \left( K^d \left[ \delta + K^{\gamma+1} \Delta t^\gamma + \sum_{i=1}^{2d} K^{q_i} \Delta z_i^{q_i} \right] + \frac{1}{(1+K)^{\frac{\alpha+1}{2}-d}} \right) \end{aligned}$$

where  $C$  is independent of  $n, \Delta t, \Delta z_i, K$ .

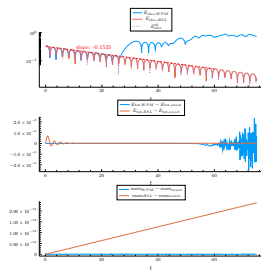
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Weighted Sobolev spaces

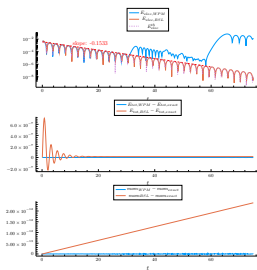
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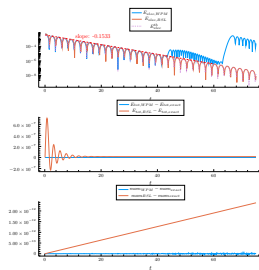
# Weak Landau damping



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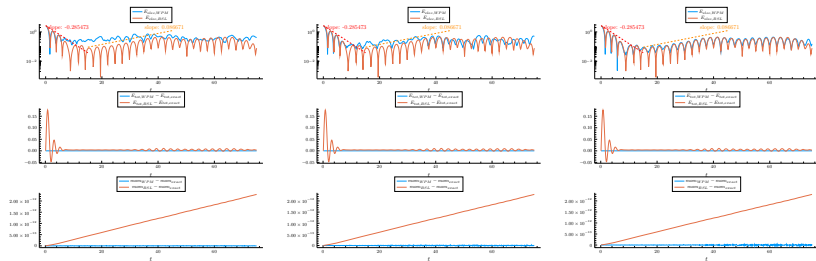


(b)  $K = 15$ ,  $N_1 = 128$ ,  
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(c)  $K = 15$ ,  $N_1 = 256$ ,  
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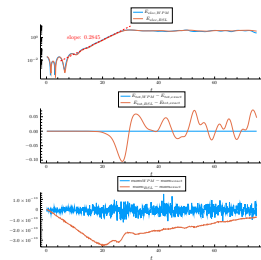


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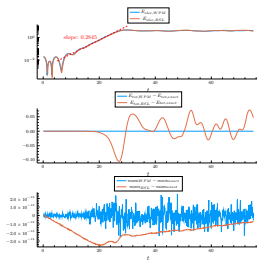
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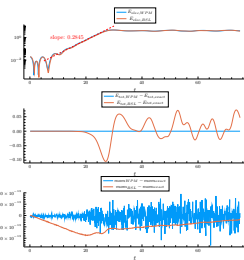
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